

Tegning af 2D-parametriseret område

Anvendelse af Integrator8-pakken

Dobbeltintegraler med ikke-faste grænser

Eksemplerne er fra Maple-demo 24a_Planintegral

Kortfattet oversigt over kommandoerne i Integrator8-pakken kan findes på Steens hjemmeside

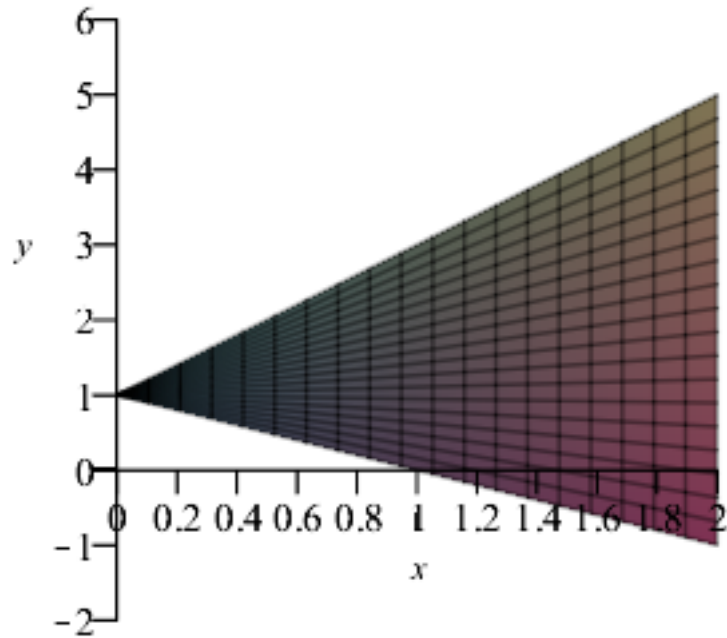
▼ Plot af parametriseret område i planen (2D)

```
[> restart  
[> with(Integrator8) :
```

▼ Eksempel 1 (trekant)

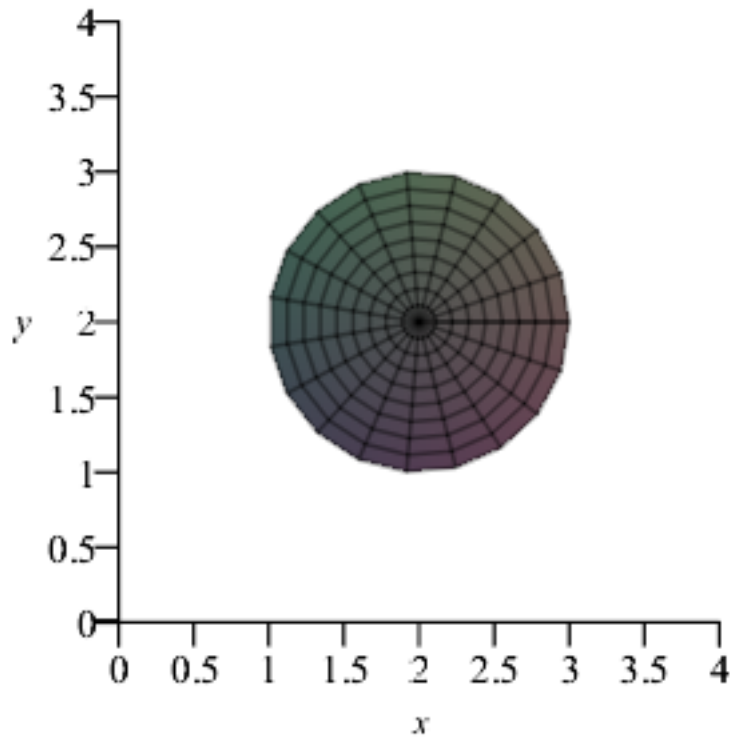
Det parametriserede 2D-område kan - *tilsyneladende* - kun tegnes ved at tegne et 3D-plot, som ses ovenfra!

```
> plot3d(⟨u, 1 - u + 3·v·u, 0⟩, u = 0 .. 2, v = 0 .. 1, labels = [x, y, ""], axes = normal,  
orientation = [-90, 0], view = [0 .. 2, -2 .. 6, -1 .. 1], tickmarks = [10, 10, 10], grid  
= [20, 20])
```



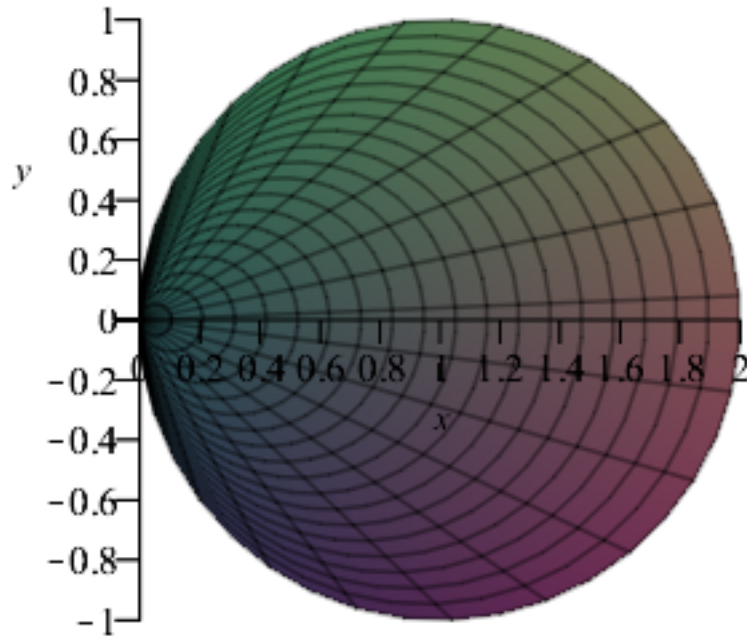
▼ Eksempel 2 (cirkel)

```
> plot3d(⟨2 + u·cos(v), 2 + u·sin(v), 0⟩, u=0..1, v=0..2·π, labels=[x, y, ""], axes  
=normal, orientation=[-90, 0], view=[0..4, 0..4, -1..1], tickmarks=[10, 10,  
10], grid=[10, 20])
```



▼ Eksempel 3 (cirkel)

```
> plot3d( $\langle 2 \cdot u \cdot \cos(v) \cdot \cos(v), 2 \cdot u \cdot \cos(v) \cdot \sin(v), 0 \rangle$ ,  $u = 0 \dots 1$ ,  $v = -\frac{\pi}{2} \dots \frac{\pi}{2}$ , labels  
= [x, y, ""], axes = normal, orientation = [-90, 0], view = [0 ..2, -1 ..1, -1 ..1],  
tickmarks = [10, 10, 10], grid = [20, 40])
```



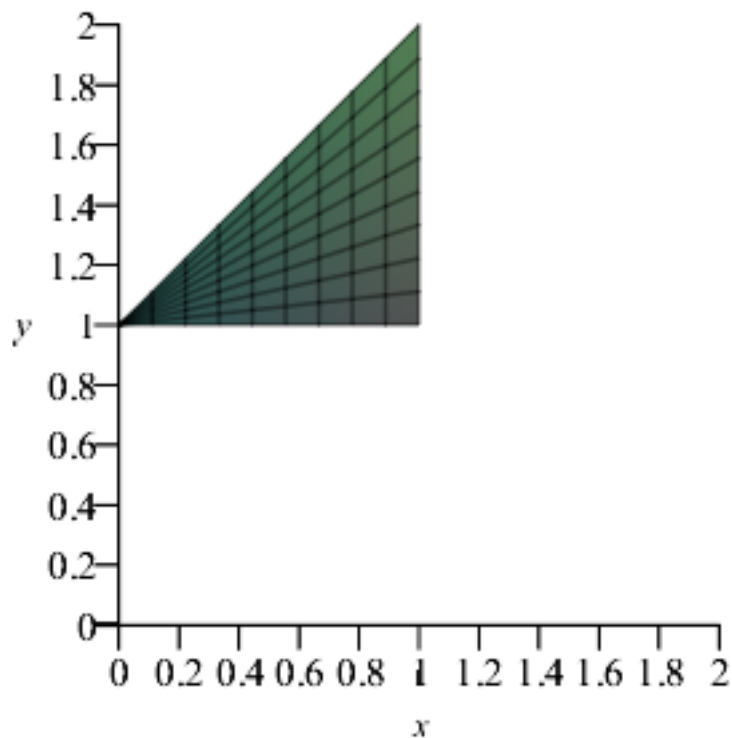
▼ Et planintegral over et trekantet område

> $r := (u, v) \rightarrow \langle u, 1 + v \cdot u \rangle : r(u, v)$

$$\begin{bmatrix} u \\ v u + 1 \end{bmatrix}$$

(1.4.1)

> `plot3d($\langle r(u, v)[1], r(u, v)[2], 0 \rangle$, $u = 0 .. 1$, $v = 0 .. 1$, $labels = [x, y, ""]$, $axes = normal$, $orientation = [-90, 0]$, $view = [0 .. 2, 0 .. 2, -1 .. 1]$, $tickmarks = [10, 10, 10]$, $grid = [10, 10]$)`



a) Beregnet med Integrator8-pakken

$$\text{> } f := (x, y) \rightarrow 2 \cdot x \cdot y : f(x, y) \quad 2yx \quad (1.4.1.1)$$

$$\text{> } B := [0, 1, 0, 1] \quad B := [0, 1, 0, 1] \quad (1.4.1.2)$$

$$\text{> } \text{planIntGo}(r, B, f) \quad \frac{11}{12} \quad (1.4.1.3)$$

b) Beregnet med *integral*, hvor grænserne ikke er konstante

Parameteren y løber mellem 1 og $x+1$ (idet den rette linje $y = x + 1$ begrænser opadtil).
Parameteren x løber mellem 0 og 1.

$$\text{> } \int_0^1 \int_1^{x+1} f(x, y) \, dy \, dx \quad \frac{11}{12} \quad (1.4.2.1)$$

[Opdelt i 2 trin:

$$\begin{aligned} &> \int_1^{x+1} f(x, y) \, dy \\ & \qquad \qquad \qquad x \left((x+1)^2 - 1 \right) \end{aligned} \tag{1.4.2.2}$$

$$\begin{aligned} &> \int_0^1 (1.4.2.2) \, dx \\ & \qquad \qquad \qquad \frac{11}{12} \end{aligned} \tag{1.4.2.3}$$

eller

Parameteren x løber mellem $y - 1$ og 1 (idet den rette linje $y = x + 1$ begrænser opadtil).
Parameteren y løber mellem 1 og 2 .

$$\begin{aligned} &> \int_1^2 \int_{y-1}^1 f(x, y) \, dx \, dy \\ & \qquad \qquad \qquad \frac{11}{12} \end{aligned} \tag{1.4.2.4}$$

Opdelt i 2 trin:

$$\begin{aligned} &> \int_{y-1}^1 f(x, y) \, dx \\ & \qquad \qquad \qquad y \left(1 - (y-1)^2 \right) \end{aligned} \tag{1.4.2.5}$$

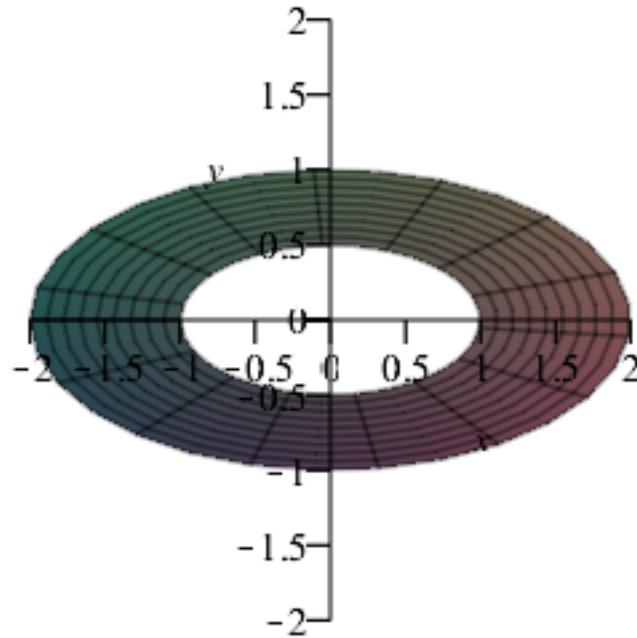
$$\begin{aligned} &> \int_1^2 (1.4.2.5) \, dy \\ & \qquad \qquad \qquad \frac{11}{12} \end{aligned} \tag{1.4.2.6}$$

▼ Et planintegral og massemidtunkt

▼ Planintegralet

$$\begin{aligned} &> r := (u, v) \rightarrow \left\langle u \cdot \cos(v), \frac{1}{2} \cdot u \cdot \sin(v) \right\rangle : r(u, v) \\ & \qquad \qquad \qquad \begin{bmatrix} u \cos(v) \\ \frac{u \sin(v)}{2} \end{bmatrix} \end{aligned} \tag{1.5.1.1}$$

$$\begin{aligned} &> \text{plot3d}(\langle r(u, v)[1], r(u, v)[2], 0 \rangle, u = 1 .. 2, v = -\pi .. \pi, \text{labels} = [x, y, ""], \text{axes} \\ & \qquad \qquad \qquad = \text{normal}, \text{orientation} = [-90, 0], \text{view} = [-2 .. 2, -2 .. 2, -1 .. 1], \text{tickmarks} \\ & \qquad \qquad \qquad = [10, 10, 10], \text{grid} = [10, 30]) \end{aligned}$$



$$\text{> } f := (x, y) \mapsto (x - 1)^2 (y + 1)^2$$

$$f := (x, y) \mapsto (x - 1)^2 (y + 1)^2$$

(1.5.1.2)

$$\text{> } B := [1, 2, -\pi, \pi]$$

$$B := [1, 2, -\pi, \pi]$$

(1.5.1.3)

$$\text{> } \text{planIntGo}(r, B, f)$$

$$\frac{267 \pi}{64}$$

(1.5.1.4)

▼ **Massemidtpunktet**

$$\text{> } \text{planCmGo}(r, B, f)$$

$$\left[-\frac{94}{89}, \frac{34}{89} \right]$$

(1.5.2.1)